

Magnetostatics (M)

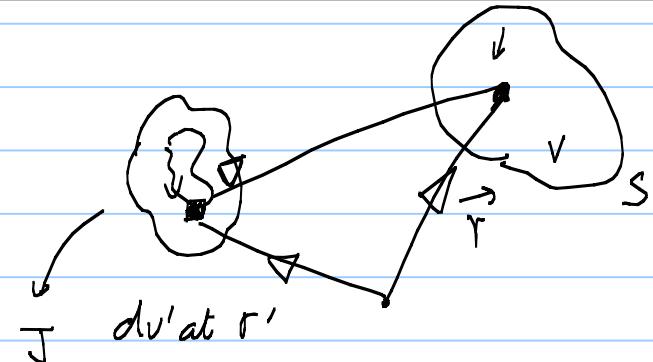
Note Title

4/1/2009

(D) Divergence of \vec{B}

$\vec{\nabla}$: gradient w.r.t \vec{r}

$\vec{\nabla}'$: gradient w.r.t \vec{r}'



$$B(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|r - r'|^3}$$

$$\nabla \cdot B(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \nabla \cdot \left[\frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|r - r'|^3} \right]$$

$$\nabla \cdot [F \times G] = G \cdot (\nabla \times F) - F \cdot (\nabla \times G)$$

$$F \text{ is ind of } \vec{r} \Rightarrow \nabla \times F = 0$$

$$= - F \cdot (\nabla \times G)$$

$$\left. \begin{aligned} F(\vec{r}') &= \bar{J}(r') \\ \vec{G}(r, r') &= \frac{(r - r')}{|r - r'|^3} \end{aligned} \right\}$$

$$\nabla \cdot \vec{B}(\vec{r}) = -\frac{\mu_0}{4\pi} \int d\vec{v}' \ J(\vec{r}') \cdot \left(\vec{J} \times \frac{(\vec{r}-\vec{r}')}{|\vec{r}-\vec{r}'|^3} \right)$$

$\underbrace{\hspace{10em}}$
 0

$$\boxed{\nabla \cdot \vec{B} = 0}$$

$$\int_V \nabla \cdot \vec{B} dV = 0$$

$$\Rightarrow \boxed{\oint_S \vec{B} \cdot d\vec{s} = 0}$$

Compare

$$\oint_S \vec{E} \cdot d\vec{s} = \frac{Q_{net}}{\epsilon_0}$$

Magnetic monopoles don't Exist

↳ Magnetic field lines are endless

Curl of \vec{B}

(ii)

(a) Example: A long st. wire, I

$$\vec{B}(s) = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

A curve in $x-y$ plane

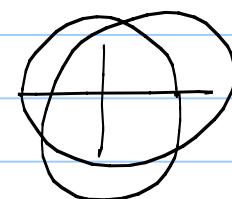
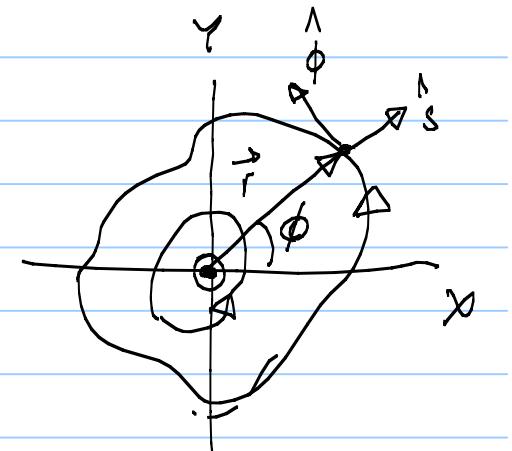
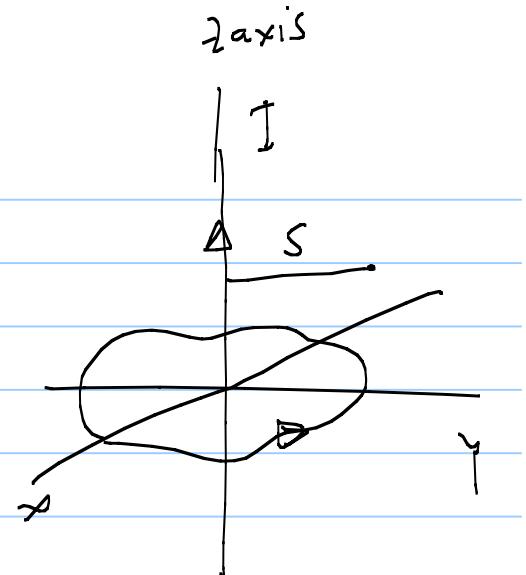
C: $\vec{r}(\phi) = (s(\phi), \phi, 0)$ in cylindrical co-ordinates

$$\phi: 0 \rightarrow 2\pi$$

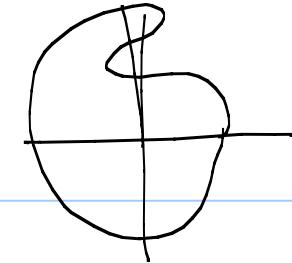
$$\vec{r}(\phi) = s(\phi) \hat{s}(\phi)$$

$$d\vec{r} = \frac{d\vec{r}}{d\phi} d\phi$$

$$= \left[\frac{ds}{d\phi} \hat{s} + s \frac{ds}{d\phi} \hat{\phi} \right] d\phi +$$



$$= \left[\frac{ds}{d\phi} \hat{s} + s \hat{\phi} \right] d\phi$$

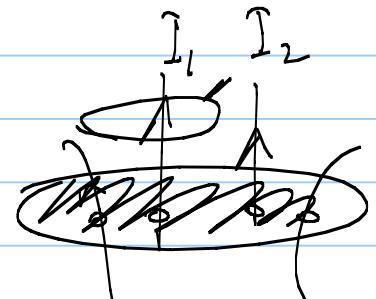
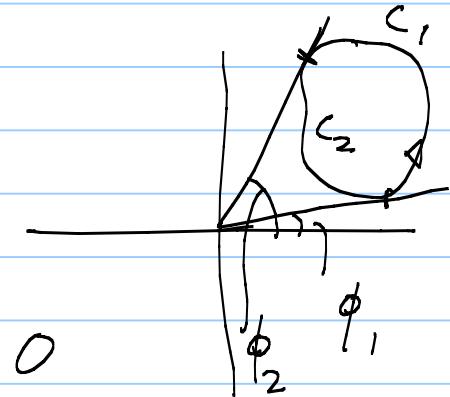


$$\oint_C \vec{B} \cdot d\vec{r} = \int_0^{2\pi} \frac{\mu_0 I}{2\pi s} \hat{\phi} \cdot \left[\frac{ds}{d\phi} \hat{s} + s \hat{\phi} \right] d\phi$$

$$= \frac{\mu_0 I}{2\pi} \int_0^{2\pi} d\phi = \underline{\mu_0 I}$$

$$\oint_C \vec{B} \cdot d\vec{r} = \int_{C_1} \vec{B} \cdot d\vec{r} + \int_{C_2} \vec{B} \cdot d\vec{r}$$

$$= \frac{\mu_0 I}{2\pi} \left[\int_{\phi_2}^{\phi_1} d\phi + \int_{\phi_1}^{\phi_2} d\phi \right] = \underline{0}$$



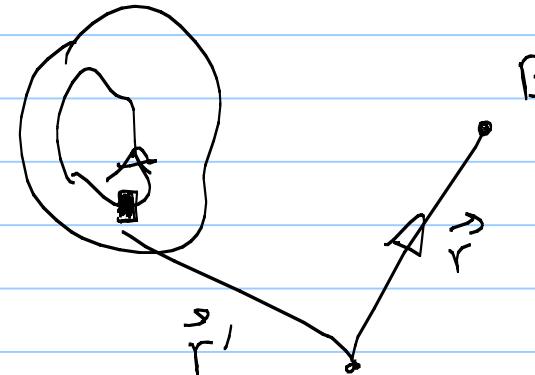
$$\oint_C \vec{B} \cdot d\vec{r} = \mu_0 I_{\text{enclosed}}$$

$$\int_S \nabla \times \vec{B} \cdot d\vec{s} = \mu_0 \int_S \vec{J} \cdot d\vec{s}$$

$$\boxed{\nabla \times \vec{B} = \mu_0 \vec{J}}$$

(b) $\vec{r} = \vec{r} - \vec{r}'$

$$\nabla \times \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \nabla \times \left[\underbrace{\vec{J}(\vec{r}')}_A \times \underbrace{\frac{\vec{r}}{r^3}}_B \right]$$



$$\nabla \times (A \times B) = (\underline{B \cdot \nabla}) A - (A \cdot \nabla) B + A (\nabla \cdot B) - B (\nabla \cdot A)$$

A is ind of \vec{r}

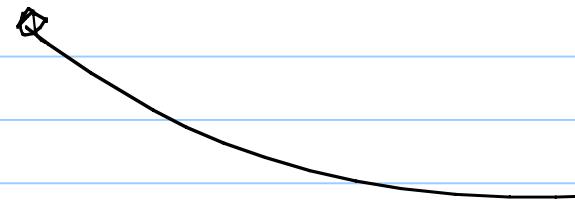
$$= A (\nabla \cdot B) - (A \cdot \nabla) B$$

$$\nabla \times \left[J(\vec{r}') \times \frac{\vec{r}}{r^3} \right] = J \left(\nabla \cdot \frac{\vec{r}}{r^3} \right) - (J \cdot \nabla) \frac{\vec{r}}{r^3}$$

$\underbrace{J}_{4\pi} \underbrace{\delta(\vec{r})}_{}$

$$\nabla \times B(\vec{r}) = \frac{\mu_0}{4\pi} \underbrace{\int d\vec{r}' J(\vec{r}') 4\pi \delta(\vec{r} - \vec{r}')}_{\text{1st term}} + \underbrace{\text{Second term}}_{\text{2nd}}$$

$$= \mu_0 J(\vec{r})$$



$$\frac{\mu_0}{4\pi} \int_S \bar{J}(\vec{r}') \frac{(x - x')}{r^3} \cdot d\vec{s}$$

$\underbrace{\qquad\qquad\qquad}_{X \text{ Component of ST}}$

$$\boxed{\nabla \times \mathbf{B} = \mu_0 \mathbf{J}}$$

$$\curvearrowleft \boxed{\oint_C \mathbf{B} \cdot d\mathbf{r} = \mu_0 I_{\text{enc}}}$$

Ampere's Law

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

Application of Ampere's Law

Ex Sheet of current with surface current density (uniform)

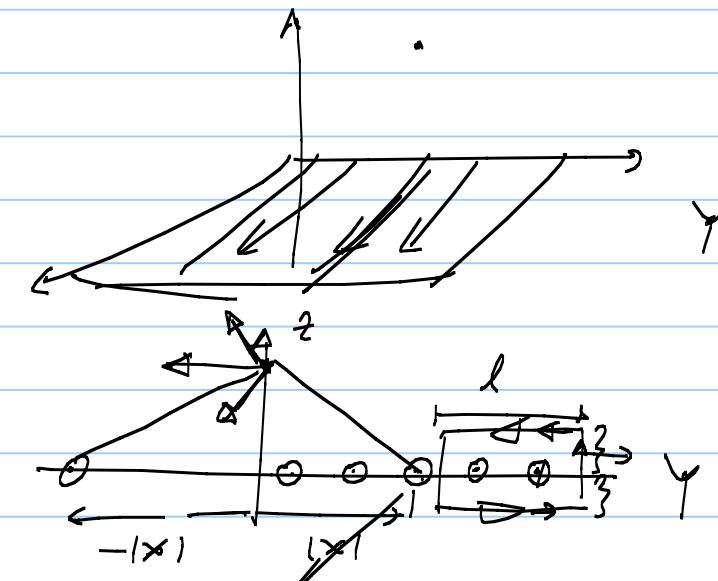


(1) $\rightarrow \mathbf{B}(z)$ only and in \hat{y} direction

$$z > 0$$

\hat{y} direction

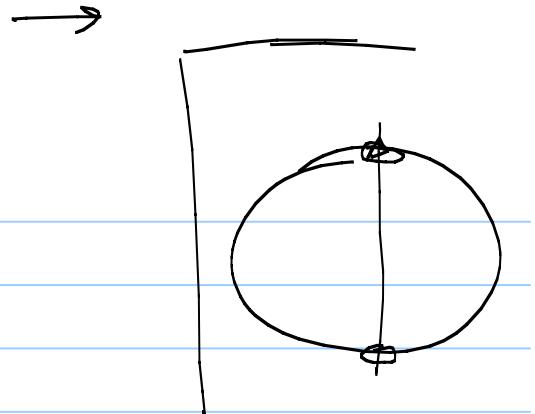
$$z < 0$$



$$B(z) \cdot l + B(z) \cdot l = \mu_0 R \cdot I$$

$$\vec{B}(z) = \frac{\mu_0 k}{2} (-\hat{y}) \quad z > 0$$

$$= \frac{\mu_0 k}{2} \hat{y} \quad z < 0$$

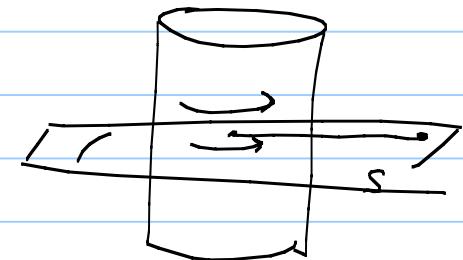
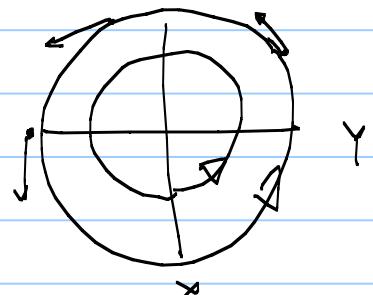


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Ex Solenoid, n turns/length, current I

$$\vec{B}(s)$$

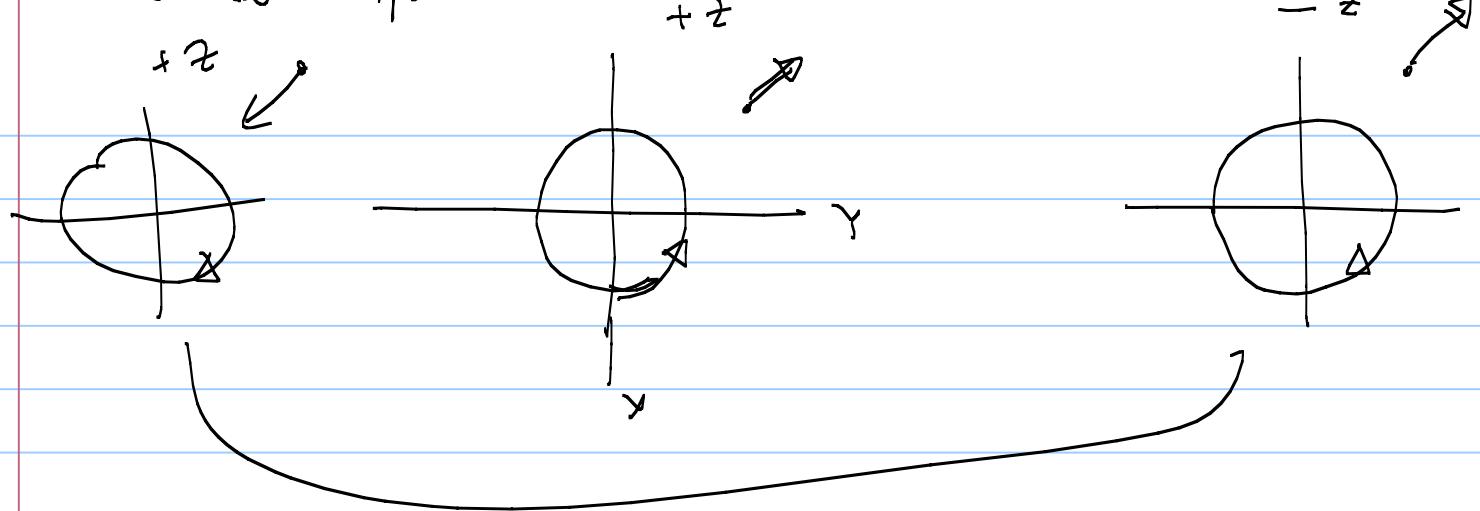
Can be have $\hat{\phi}$ component?



$$\oint \vec{B} \cdot d\vec{l} > 0 \quad \text{if } B_\phi > 0$$

$$\Rightarrow B_\phi = 0$$

Radial component



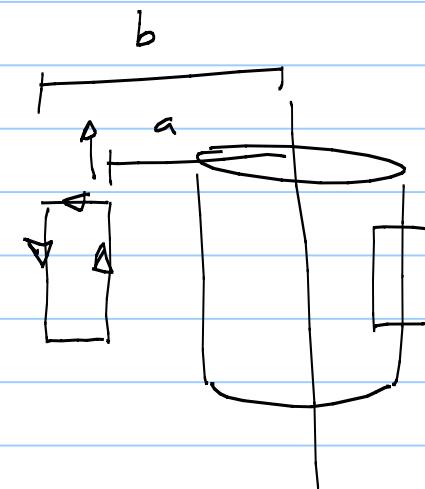
$$\Rightarrow B_r = 0$$

$$\vec{B} = B_z(s) \hat{z}$$

$$B(a) \cdot l + 0 + (-B(b)) \cdot l + 0 = 0$$

$$B(a) = B(b) = B(\infty) = 0$$

Inside $\vec{B} = \mu_0 n I \hat{z}$ outside $\vec{B} = 0$



Magnetic Vector Potential

$$\text{In ES: } \nabla \times \vec{E} = 0 \Rightarrow \vec{E} = -\nabla \phi \quad \nabla \times (\nabla \phi) = 0$$
$$\text{MS: } \nabla \cdot \vec{B} = 0 \Rightarrow \vec{B} = \nabla \times \vec{A} \quad \nabla \cdot (\nabla \times \vec{A}) = 0$$

Magnetic Vector potential.

- \vec{A} → Theoretical importance

In ES Electric Potential not unique

$$\vec{E} \rightarrow V_1(\vec{r})$$

$$V_2(\vec{r}) = V_1(\vec{r}) + C$$

In MS

$$\vec{B} \rightarrow A_1(\vec{r})$$

A is not unique

$$\vec{A}_2(\vec{r}) = \vec{A}_1(\vec{r}) + \nabla \lambda$$

λ : any scalar field

$$\begin{aligned}\nabla \times \vec{A}_2 &= \nabla \times \vec{A} + \nabla \times (\nabla \lambda) \\ &= \vec{B}\end{aligned}$$

choose divergence less vector potential, choose \mathbf{A} s.t

$$\nabla \cdot \mathbf{A} = 0$$

suppose $\nabla \cdot \mathbf{A}_1 \neq 0$

$$\nabla \cdot \mathbf{A}_2 = 0 = \nabla \cdot \mathbf{A}_1 + \nabla \cdot (\nabla \lambda)$$

$$\nabla^2 \lambda = -\underline{\nabla \cdot \mathbf{A}_1} = -\mathbf{J}$$

Poisson
Eq.

Differential Eq for Vector potential

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

$$\Rightarrow \nabla \times (\nabla \times \mathbf{A}) = \mu_0 \mathbf{J}$$

$$\Rightarrow \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$$

$$\Rightarrow \nabla^2 \bar{\mathbf{A}} = -\mu_0 \bar{\mathbf{J}} \quad \nabla \cdot \mathbf{A} = 0$$

Three Poisson Eq.

$$\Rightarrow \begin{aligned} \nabla^2 A_x &= -\mu_0 J_x \\ \nabla^2 A_y &= -\mu_0 J_y \\ \nabla^2 A_z &= -\mu_0 J_z \end{aligned} \quad \left. \begin{array}{l} \text{Only} \\ \text{in} \\ \text{Cartesian Co-ordinates} \end{array} \right]$$

$$\nabla^2 A_r = -\mu_0 J_r$$

$$A_x = \frac{\mu_0}{4\pi} \int \frac{J_x(r') dv'}{|r - r'|}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(r') dv'}{|r - r'|}$$

In Es

$$\nabla^2 V = -\frac{\rho}{\epsilon_0}$$

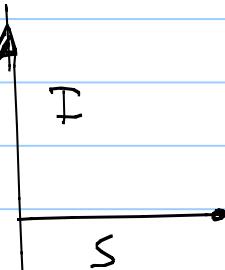
$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(r') dv'}{|r - r'|}$$

Ex $\vec{A} = A_z(s) \hat{z}$

$$\vec{\nabla} \times \vec{A} = -\hat{\phi} \frac{\partial A_z}{\partial s} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

$$A_z = -\frac{\mu_0 I}{2\pi} \ln s$$

$$\vec{A} = -\frac{\mu_0 I}{2\pi} \ln s \hat{z}$$



$$\bar{\nabla} \cdot \bar{A} = \frac{\partial}{\partial z} A_z = 0$$

Ex $\vec{B} = \mu_0 n \bar{I} \hat{z}$ inside
 $= 0$ outside

$$\vec{A} = A_\phi(s) \hat{\phi}$$

$$(\bar{\nabla} \times \bar{A})_\phi = \frac{1}{s} \frac{\partial}{\partial s} (s A_\phi) = \mu_0 n \bar{I}$$

$$A_\phi = \frac{\mu_0 n \bar{I} s}{2}$$

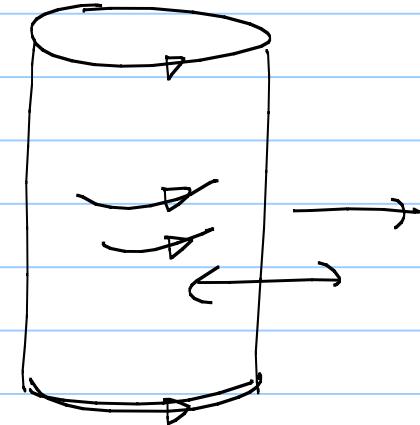
$$\vec{A} = \frac{\mu_0 n \bar{I} s}{2} \hat{\phi}$$

inside

$$\vec{A} = \frac{C}{s} \hat{\phi}$$

outside

$$= \frac{\mu_0 n \bar{I} a^2}{2s} \hat{\phi}$$



outside

$$\frac{1}{s} \frac{\partial}{\partial s} (s A_\phi) = 0$$

$$s A_\phi = C$$

$$A_\phi = \frac{C}{s}$$

Ex Sphere with surface charge density σ
 Sphere is spinning with ang. Vel. $\vec{\omega}$

$$\vec{r} = r \hat{z}$$

$$\vec{\omega} = (\omega \sin \psi, 0, \omega \cos \psi) \quad \leftarrow$$

$$r' = (R, \theta', \phi') \text{ in sph}$$

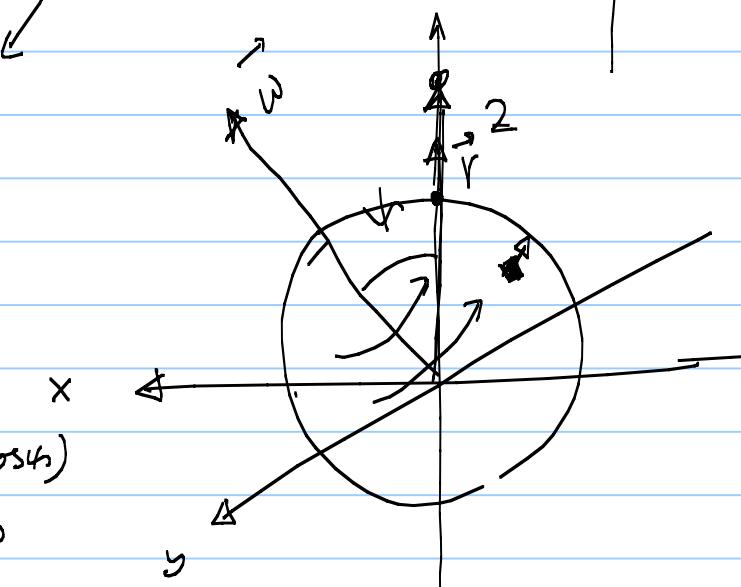
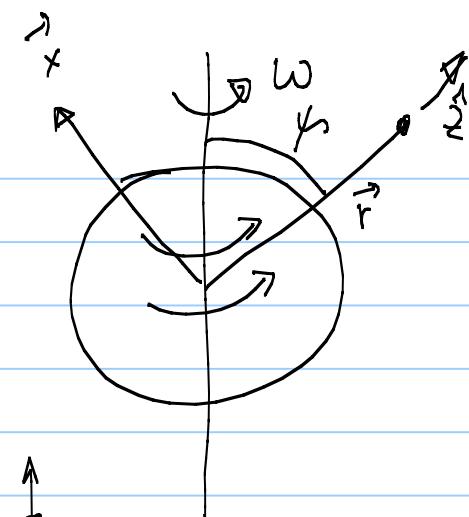
$$= (R \sin \theta' \cos \phi', R \sin \theta' \sin \phi', R \cos \theta') \quad \leftarrow$$

$$d\alpha' = R^2 \sin \theta d\theta d\phi$$

$$\vec{v} \text{ at } r' = \vec{\omega} \times \vec{r}'$$

$$= [\begin{matrix} \hat{x} & (-\cos \psi \sin \theta' \sin \phi') \\ \hat{y} & (-\sin \psi \cos \theta' + \sin \theta' \cos \phi' \cos \psi) \\ \hat{z} & (\sin \psi \sin \theta' \sin \phi') \end{matrix}] R \omega$$

$$\vec{k} = \sigma \vec{v} = \sigma R \omega [$$



$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{k(r') da'}{|r - r'|} d\phi'$$

$$= -\frac{\mu_0}{4\pi} \sigma R_w^2 \int \frac{\hat{\psi}(\sin\theta \cos\phi') \sin\theta' d\theta' d\phi'}{(r^2 + R^2 - 2Rr \cos\theta')^{1/2}}$$

Vector Potential

Note Title

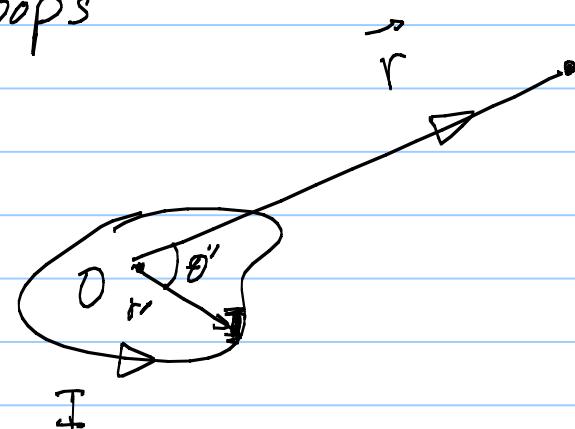
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Multipole Expansion $\frac{1}{r}$ only loops

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \oint \frac{I \vec{dl}'}{|\vec{r} - \vec{r}'|} \rightarrow K da'$$

$$\frac{1}{|\vec{r} - \vec{r}'|} = \frac{1}{r} \sum_{n=0}^{\infty} \left(\frac{r'}{r} \right)^n P_n(\cos\theta')$$

$$= \frac{1}{r} + \frac{r'}{r^2} \cos\theta' + \frac{r'^2}{r^3} \left(\frac{3\cos^2\theta' - 1}{2} \right) + \dots$$



$$\vec{A}(\vec{r}) = \underbrace{\frac{\mu_0 I}{4\pi r} \oint d\vec{l}}_{\text{Monopole term}} + \underbrace{\frac{\mu_0 I}{4\pi r^2} \oint r' \cos\theta' d\vec{l}'}_{\text{dipole term}} + \dots$$

\vec{O}' pole term

Monopole term = 0 \Rightarrow Monopole Moment = 0
 Monopole don't Exist!

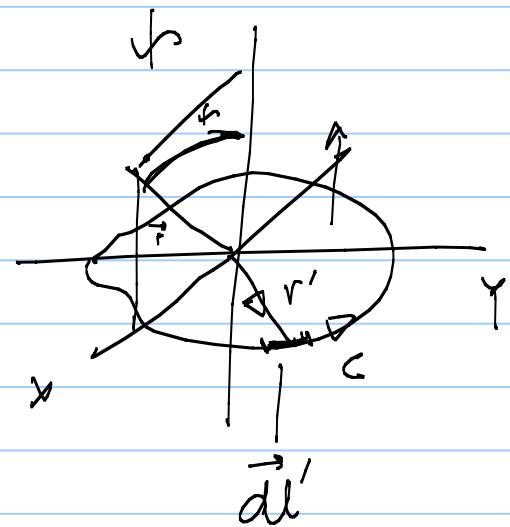
$$A_{\text{dip}}(\vec{r}) = \frac{\mu_0 I}{4\pi r^2} \oint r' \cos\phi' d\vec{l}' \Rightarrow$$

Planar loop: C in XY plane (r', θ_z^I, ϕ')

Angle between \vec{r} and \vec{r}'

$$\cos\phi' = \sin\psi \cos\phi'$$

$$d\vec{l}' = dx' \hat{x} + dy' \hat{y}$$

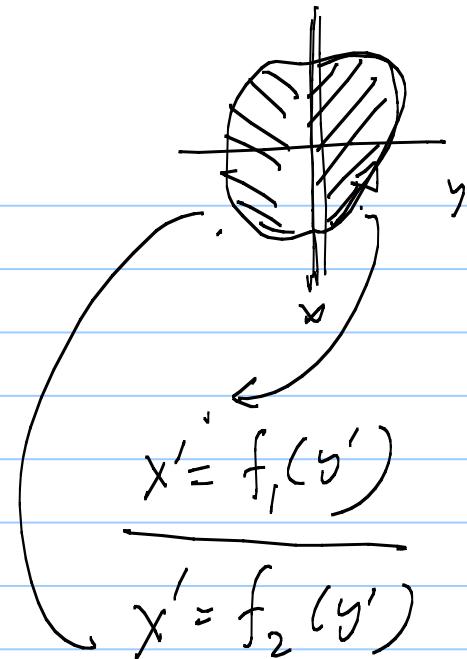


$$\vec{A}_{\text{dip}} = \frac{\mu_0 I \sin\psi}{4\pi r^2} \oint r' \cos\phi' (dx' \hat{x} + dy' \hat{y}) \quad \left. \begin{array}{l} \vec{r} = (r \sin\psi, \phi, r \cos\psi) \\ \vec{r}' = (r' \cos\phi', r' \sin\phi', \phi) \end{array} \right\}$$

$$= \frac{\mu_0 I \sin \psi}{4\pi r^2} \left[\hat{x} \int x' dx' + \hat{y} \int x' dy' \right]$$

$$= \frac{\mu_0 I \sin \psi}{4\pi r^2} \left[0 + \hat{y} \int x' dy' \right]$$

total area of loop = a



$$= \frac{\mu_0 I a \sin \psi}{4\pi r^2} \hat{y}$$

$$\rightarrow m = I(\hat{a} \hat{z}) = \text{dipole moment}$$

$$= \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$$

Co-ordinate free form

$$\vec{r} = \hat{x} r \sin \psi + \hat{z} r \cos \psi$$



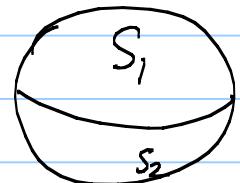
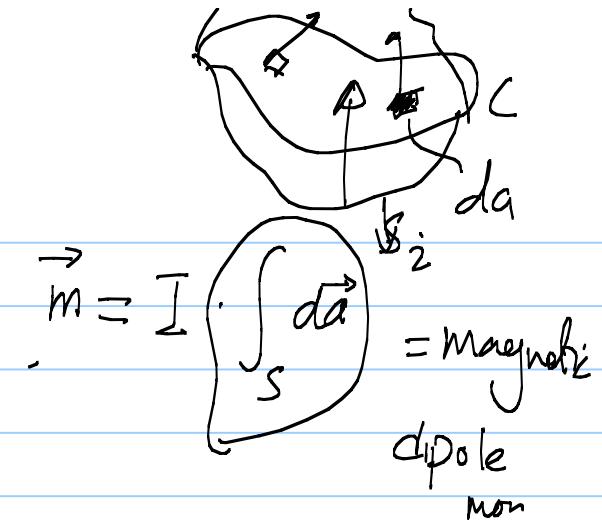
Non planar loops (tut problem)

$$A_{\text{dip}}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^2}$$

$S_1 + S_2$ is closed

$$\int_{S_1 + S_2} \vec{da} = 0$$

$$\int_{S_1} \vec{da} = - \int_{S_2} \vec{da}$$



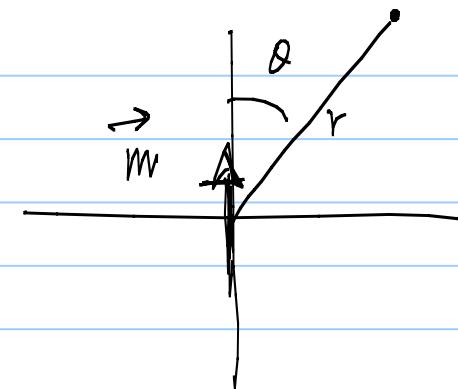
$$\oint da = 4\pi R^2$$

$$\oint \vec{da} = 0$$

Pole dipole is where only dipole term is nonzero

$$\vec{m} = m \hat{z}$$

$$A(r, \theta, \phi) = \frac{\mu_0}{4\pi} \frac{m \sin\theta}{r^2} \hat{\phi}$$

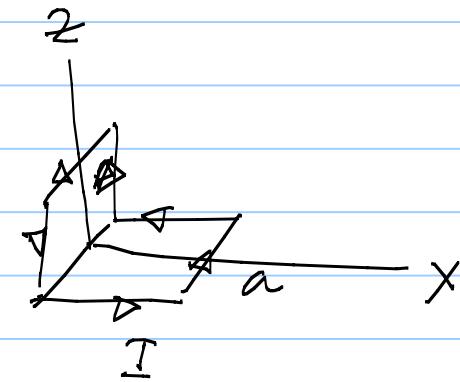


$$\vec{B}(r, \theta, \phi) = \nabla \times \vec{A}$$

$$= \frac{\mu_0 m}{4\pi r^3} \left[\hat{r} 2 \cos\theta + \hat{\theta} \sin\theta \right]$$

\vec{m} is additive

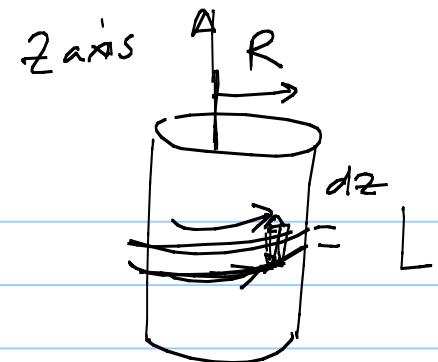
$$\text{Ex } \vec{m} = Ia^2 \left[\hat{z} + \hat{x} \right]$$



Ex Solenoid of L and

$$nI$$

$$\vec{m} = nI\pi R^2 L \frac{1}{2}$$



Lorentz Force Law

Expt Fact (Law)

A point charge in magnetic field

$$F_{\text{mag}} = q(\vec{v} \times \vec{B})$$

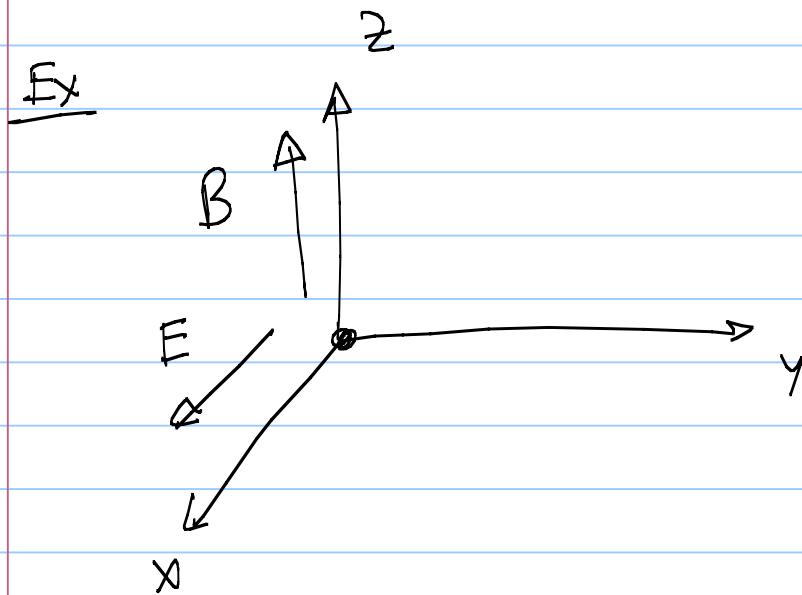
$$\left[\int d\vec{a}' \int d\vec{l}' dz \right]$$

$$\bullet \rightarrow \vec{v}$$

$$q \quad \vec{B}$$

if E present

$$\vec{F} = q(E + \vec{v} \times \vec{B})$$



Given $\vec{B} = B \hat{z}$ $E = E \hat{x}$

Point charge q , mass m is released from origin.

Find the trajectory:

point charges

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q \vec{v} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

if a point chay

q has velocity \vec{v}

Field due to pt. chay

?

$$\vec{r} = (x(t), y(t), z(t)) \quad \vec{v} = (v_x(t), v_y(t), v_z(t))$$

$$m \vec{a} = q(E + \vec{v} \times \vec{B})$$

$$\vec{v} \times \vec{B} = \begin{bmatrix} \hat{x} & \hat{y} & \hat{z} \\ v_x & v_y & v_z \\ 0 & 0 & B \end{bmatrix}$$

$$= \hat{x}(v_y B) - v_x B \hat{y}$$

$$m(\ddot{x}\hat{x} + \ddot{y}\hat{y} + \ddot{z}\hat{z}) = \hat{x}(qE + qv_y B) + (-v_x B q) \hat{y}$$

$$\ddot{z} = 0 \Rightarrow z = A + Bt \quad \begin{aligned} z(0) &= 0 \\ \dot{z}(0) &= 0 \end{aligned}$$

$$\dot{v}_y = -\frac{qB}{m} v_x$$

$$\dot{V}_x = \frac{qE}{m} + \frac{qB}{m} V_y$$

$$\ddot{V}_x = \left(\frac{qB}{m} \right) \dot{V}_y = - \left(\frac{qB}{m} \right)^2 V_x = - \omega^2 V_x$$

$$V_x = A \sin(\omega t) + B \cos(\omega t)$$

$$V_x(0) = 0$$

$$= A \sin(\omega t)$$

$$V_y = \frac{A\omega \cos \omega t}{\omega} - \frac{qE}{mw}$$

$$= A \cos \omega t - \frac{E}{B}$$

$$V_y(0) = 0$$

$$= \frac{E}{B} (\cos \omega t - 1)$$

$$\dot{x} = \frac{E}{B} \sin \omega t$$

$$x(t) \rightarrow$$

Cycloid.