

First Law of Motion

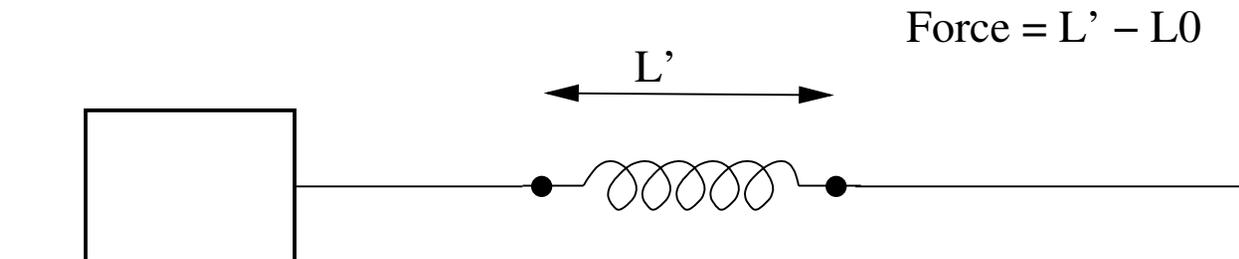
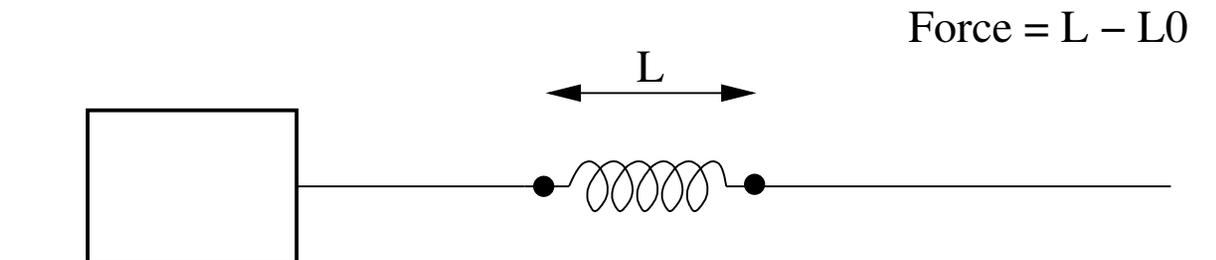
Isolated bodies move with uniform velocity.

- Common Notion: All moving bodies come to a halt.
- Friction is just another *force*, like pushing by a hand.
- Isolated Bodies
- Inertial Frames

Second Law of Motion

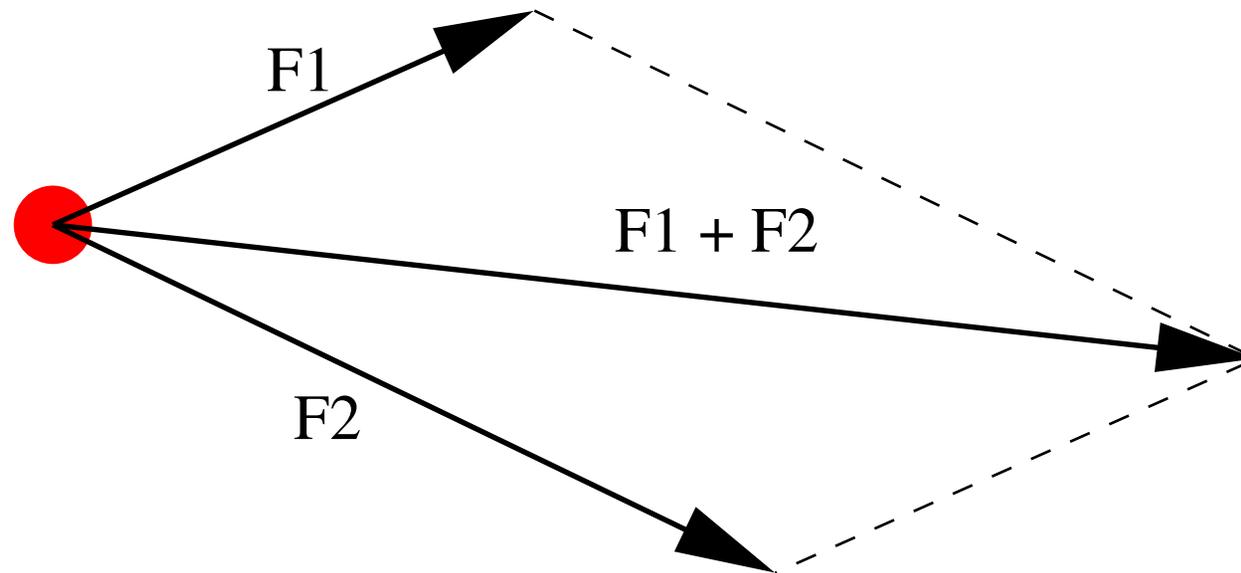
$$F = \frac{d}{dt} (mv) = ma$$

- It is a law, not a definition!
- Force: a spring force



Second Law of Motion

- Mass is a measure of inertia
- Force is a vector quantity.



Third Law of Motion

Every action has a reaction

- Describes the nature of forces
- Is it always true?
There is some problem with electromagnetic forces.

Fundamental Forces

- Gravitational Forces
- Electromagnetic Forces
- Weak Nuclear Forces
- Strong Nuclear Forces

Gravitational Forces

- Tycho Brahe and Kepler
- Newton's Law of Gravitation

$$\mathbf{F} = G \frac{mm'}{r^2} \hat{\mathbf{r}}$$

- Inertial or gravitational Mass?
- Explains planetary Motion (Large distances)
- Cavendish Experiment (On Earth)

Electrical and Magnetic Forces

- Coulomb's Law

$$\mathbf{F} = \frac{qq'}{r^2} \hat{\mathbf{r}}$$

- Magnetic Force
- Fields \mathbf{E} and \mathbf{B}
- Lorentz Force

$$\mathbf{F} = q (\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Nuclear Forces

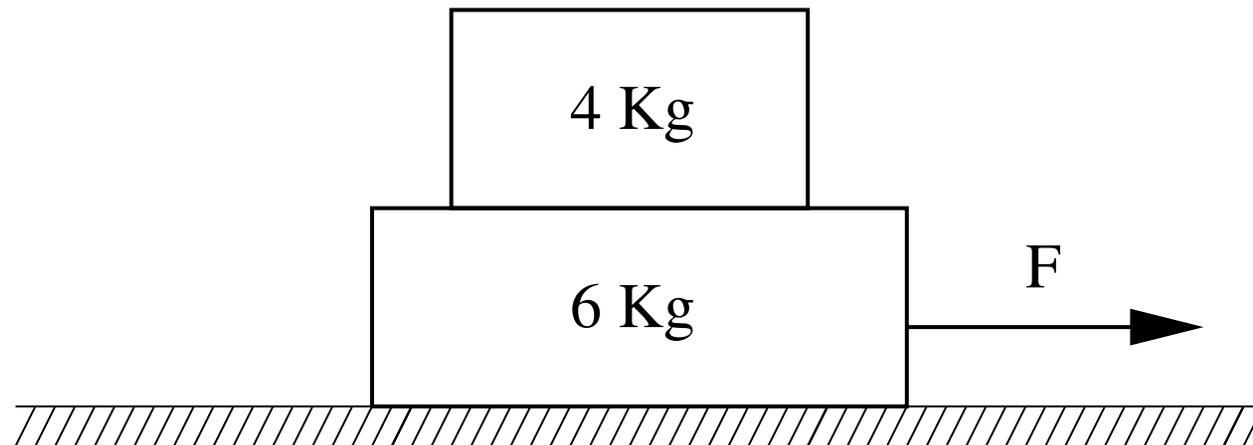
- Range of Nuclear Forces
- Scattering Experiments
- Newtonian or Quantum Mechanics?

Everyday Forces

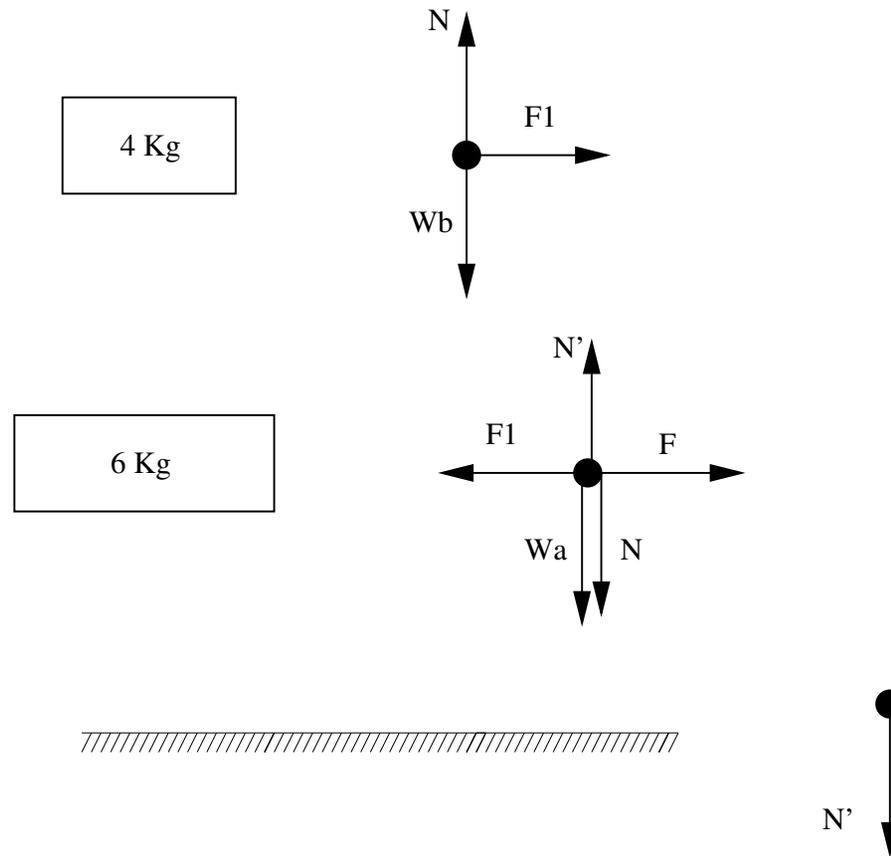
- Tension in the ropes
- Normal Forces
- Frictional Forces
- Viscous Forces
- Springs
- Atomic Forces

Examples

A 4 Kg block rests on top of a 6 Kg block, which rests on a frictionless table. Coefficient of friction between blocks is 0.25. A force $F = 10N$ is applied to the lower block.

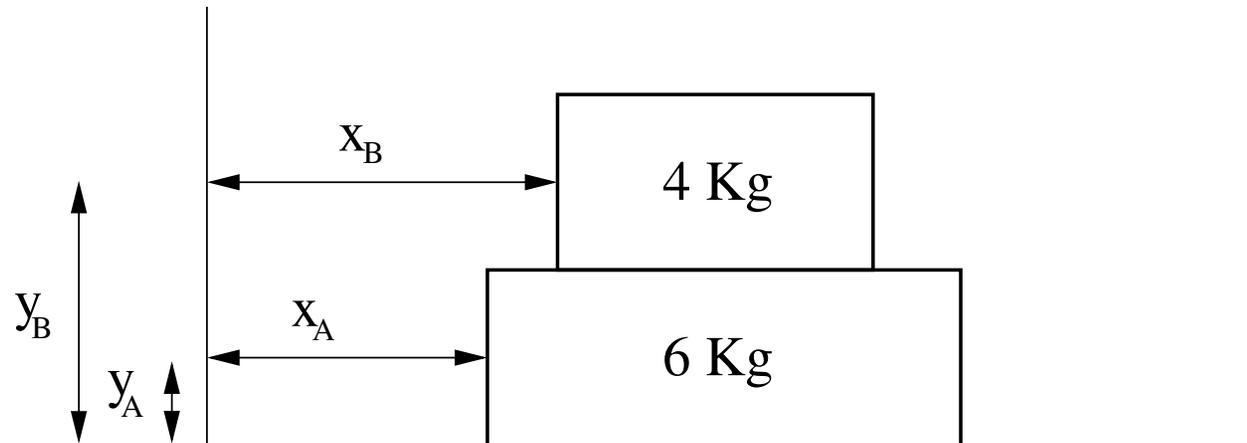


Force Diagrams



Coordinate System and Constraints

Fix the coordinate system to the table.



$$y_A = \text{const}$$

$$y_B = \text{const}$$

$$x_A = x_B + \text{const}$$

Equations

Equations of Motion in Y direction.

$$m_A \ddot{y}_A = N' - W_A - N$$

$$m_B \ddot{y}_B = N - W_B$$

Constraints

$$\ddot{y}_A = 0$$

$$\ddot{y}_B = 0$$

Solution

$$N' = W_A + W_B$$

$$N = W_B$$

Equations

Equations of Motion in X direction.

$$m_A \ddot{x}_A = F - F_1$$

$$m_B \ddot{x}_B = F_1$$

Constraints

$$\ddot{x}_A = \ddot{x}_B$$

Solution

$$\ddot{x}_A = \ddot{x}_B = \frac{F}{m_A + M_B} = 1\text{m/s}^2$$

$$F_1 = m_B \ddot{x}_B = 4\text{N}$$

Example Continued...

- The force $F_1 < \mu N = 10$ N, the maximum frictional force between the blocks. Hence the solution is consistent with assumption.
- What would be the motion if $F = 40$ N?
If the blocks move together then $x_B = 4$ m/s and $F_1 = 16$ N! More than the maximum frictional force!

Equations

Equations of Motion in X direction.

$$m_A \ddot{x}_A = F - F_1$$

$$m_B \ddot{x}_B = F_1$$

But,

$$F_1 = \mu N$$

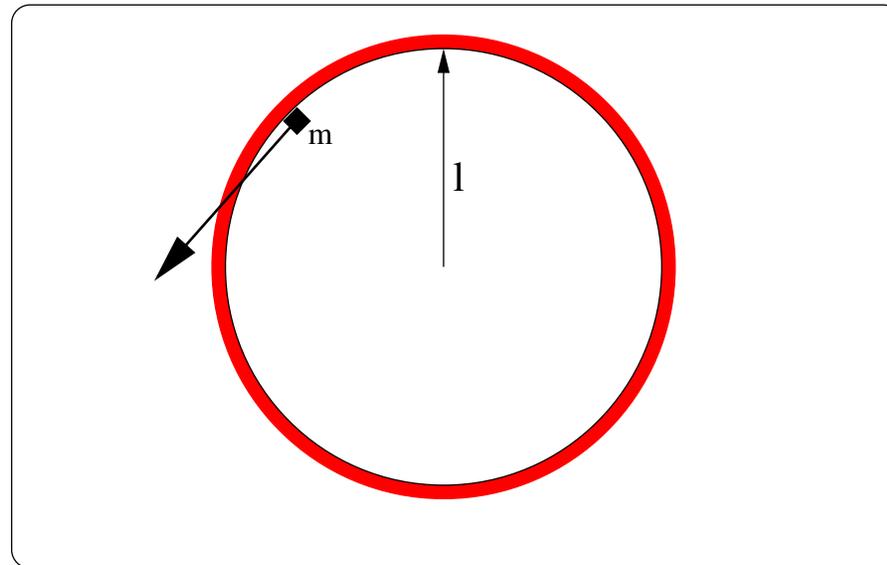
Solution

$$\ddot{x}_A = \frac{F - \mu N}{m_A} = 5\text{m/s}^2$$

$$\ddot{x}_B = \frac{\mu N}{m_B} = 2.5\text{m/s}^2$$

Another Example

A block of mass m slides on a frictionless table. It is constrained to move inside a ring of radius l fixed to the table. At $t = 0$ the block is touching the ring and has a velocity v_0 in tangential direction.



Equations

- Constraint Equation is $r = l$, that is $\dot{r} = \ddot{r} = 0$.
- Equations of Motion

$$m \left(\ddot{r} - r\dot{\theta}^2 \right) = -ml\dot{\theta}^2 = -N$$

$$m \left(r\ddot{\theta} - 2\dot{r}\dot{\theta} \right) = mr\ddot{\theta} = -f$$

- Eliminating N , we get

$$\begin{aligned} \ddot{\theta} &= -\mu\dot{\theta}^2 \\ v(t) &= l\dot{\theta} \\ &= \frac{v_0}{1 + \mu v_0 t / l} \end{aligned}$$