
Physics I

Lecture 11

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Rotating Coordinate Systems

Transformation Equations

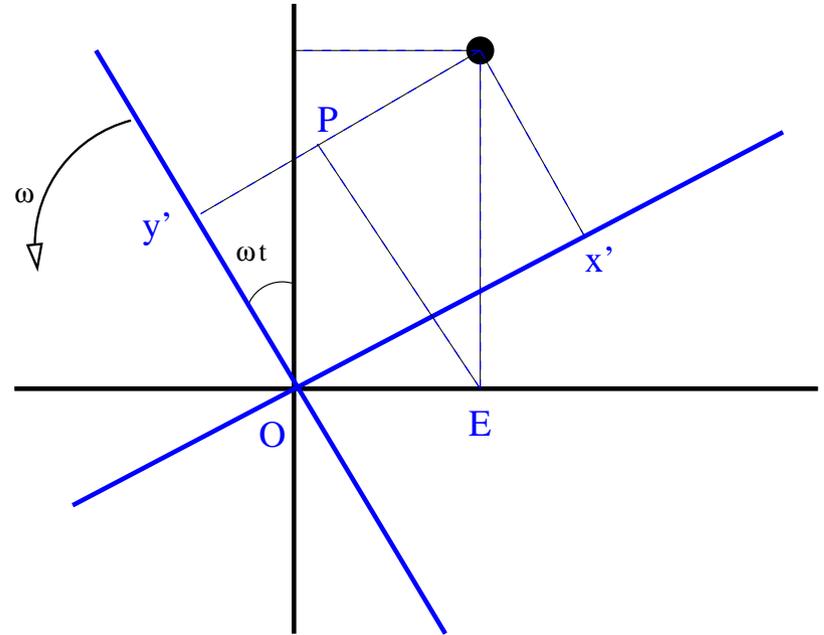
$$x' = x \cos \omega t + y \sin \omega t$$

$$y' = -x \sin \omega t + y \cos \omega t$$

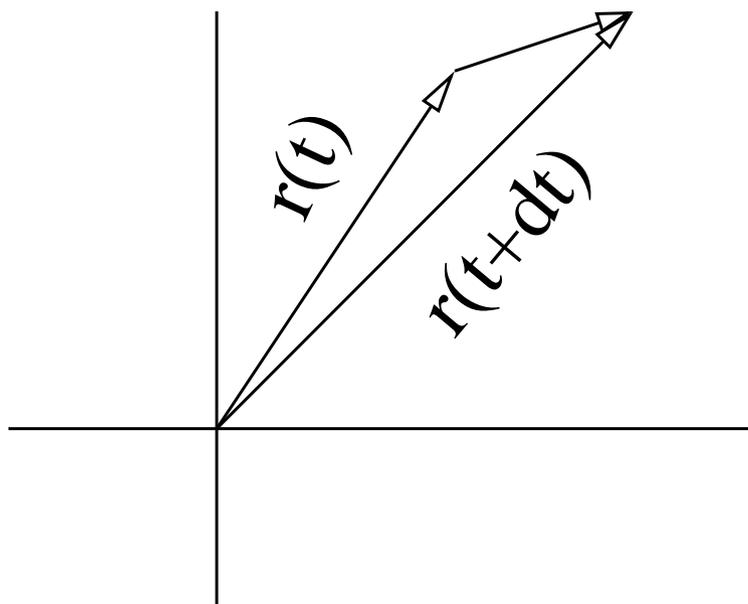
The unit vectors also change with time

$$\mathbf{i}' = \mathbf{i} \cos \omega t - \mathbf{j} \sin \omega t$$

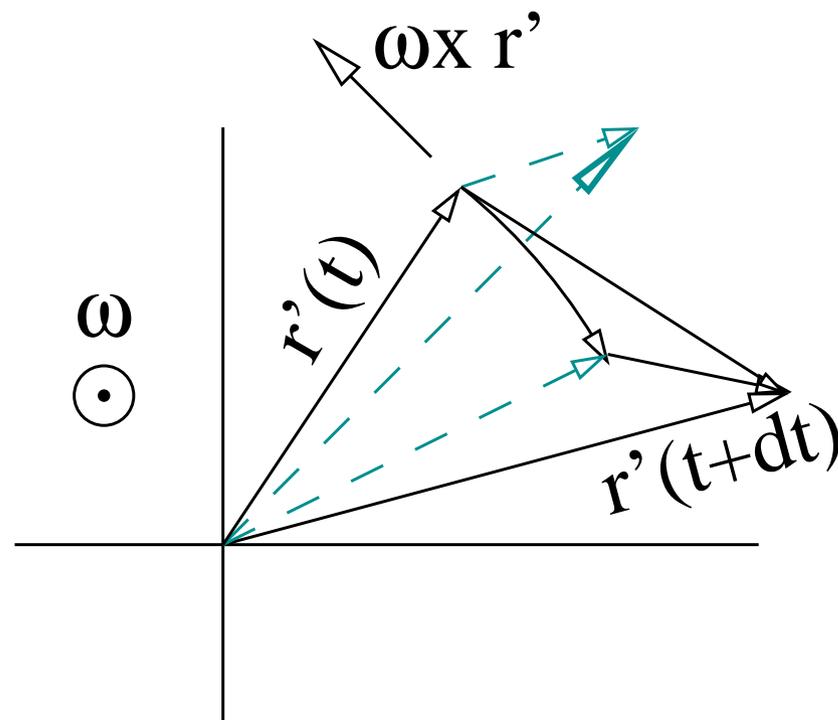
$$\mathbf{j}' = \mathbf{i} \sin \omega t + \mathbf{j} \cos \omega t$$



Rotating Coordinate Systems



Fixed Frame



Rotating Frame

$$\vec{u} = \vec{u}' + \vec{\omega} \times \vec{r}'$$

Rotating Coordinate Systems

Inverse Transformations

$$x = x' \cos \omega t - y' \sin \omega t$$

$$y = x' \sin \omega t + y' \cos \omega t$$

Velocity Vector

$$\begin{aligned} u_x &= \frac{dx}{dt} \\ &= \frac{dx'}{dt} \cos \omega t - \frac{dy'}{dt} \sin \omega t - x' \omega \sin \omega t - y' \omega \cos \omega t \end{aligned}$$

Rotating Coordinate Systems

$$\mathbf{i}u_x = u'_x \mathbf{i} \cos \omega t - u'_y \mathbf{i} \sin \omega t - x' \omega \mathbf{i} \sin \omega t - y' \omega \mathbf{i} \cos \omega t$$

$$\mathbf{j}u_y = u'_x \mathbf{j} \sin \omega t + u'_y \mathbf{j} \cos \omega t + x' \omega \mathbf{j} \cos \omega t - y' \omega \mathbf{j} \sin \omega t$$

$$\begin{aligned} \vec{u} &= u'_x \mathbf{i}' + u'_y \mathbf{j}' + x' \omega \mathbf{j}' - y' \omega \mathbf{i}' \\ &= \vec{u}' + \omega x' (\mathbf{k}' \times \mathbf{i}') + \omega y' (\mathbf{k}' \times \mathbf{j}') \\ &= \vec{u}' + \vec{\omega} \times \vec{r}' \end{aligned}$$

Rotating Coordinate Systems

Acceleration Vector

$$u_x = \frac{dx'}{dt} \cos \omega t - \frac{dy'}{dt} \sin \omega t - x' \omega \sin \omega t - y' \omega \cos \omega t$$

It turns out to be

$$\vec{a} = \vec{a}' + 2 \left(\vec{\omega} \times \vec{u}' \right) + \vec{\omega} \times \left(\vec{\omega} \times \vec{r}' \right)$$

Rotating Coordinate Systems

If S is inertial then $m \vec{a} = \vec{F}$

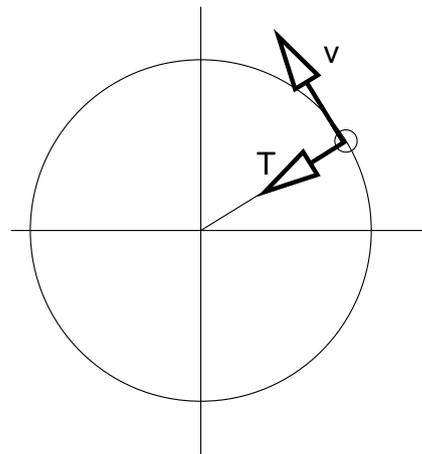
$$m \vec{a}' = \vec{F} - 2m (\vec{\omega} \times \vec{u}') - m \vec{\omega} \times (\vec{\omega} \times \vec{r}')$$

$-2m (\vec{\omega} \times \vec{u}')$ is called Coriolis Force

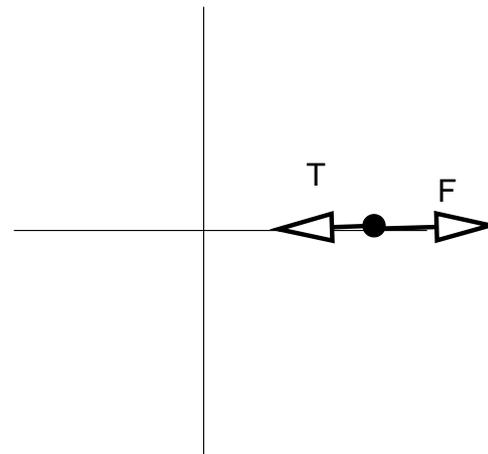
$-m \vec{\omega} \times (\vec{\omega} \times \vec{r}')$ is called Centrifugal Force

Example 1

Suppose particle is tied by a string and is in uniform circular motion in fixed frame with angular speed ω . In a frame rotating with same angular speed the particle will be at rest. Since $u' = 0$, only pseudo force is centrifugal force, which is $-m\vec{\omega} \times (\vec{\omega} \times \vec{r}') = m\omega^2 r' \hat{\mathbf{r}}'$. Free body diagrams in two frames are given below.



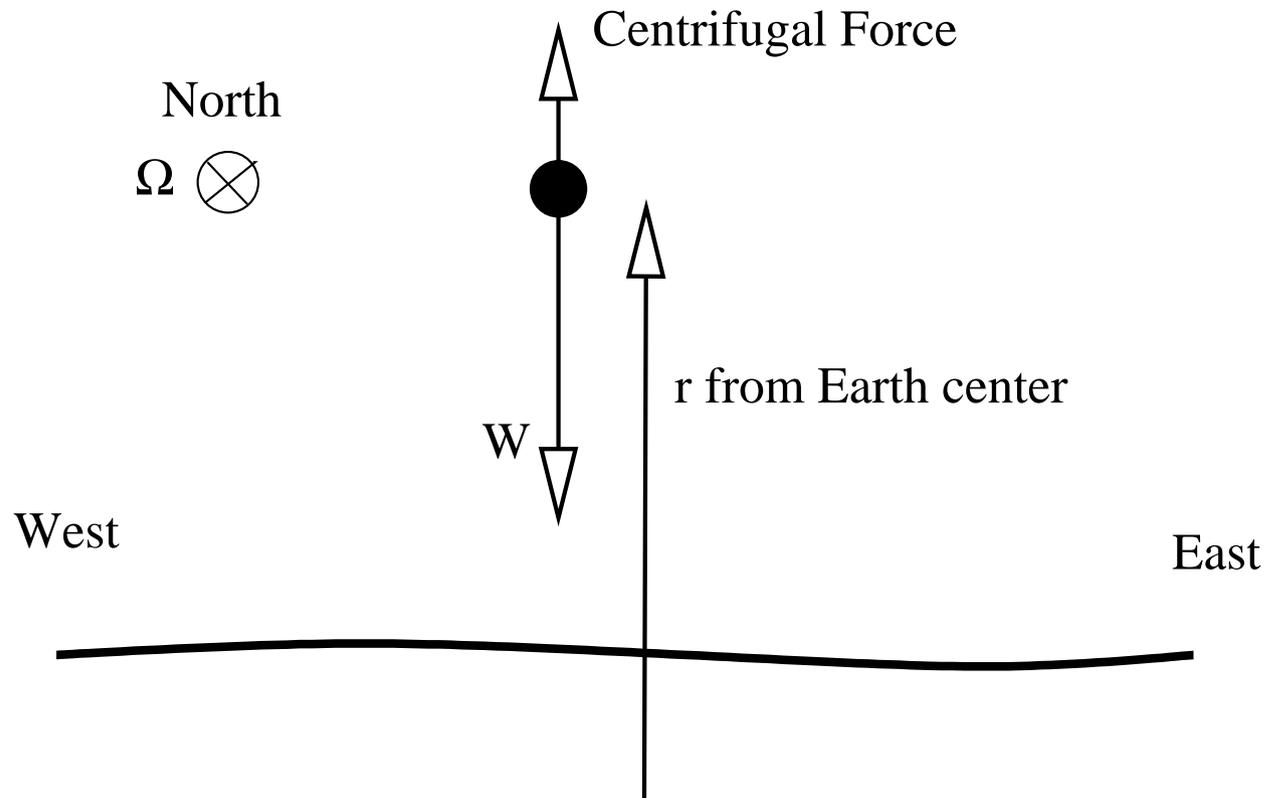
Fixed Frame



Rotating Frame

Example 2

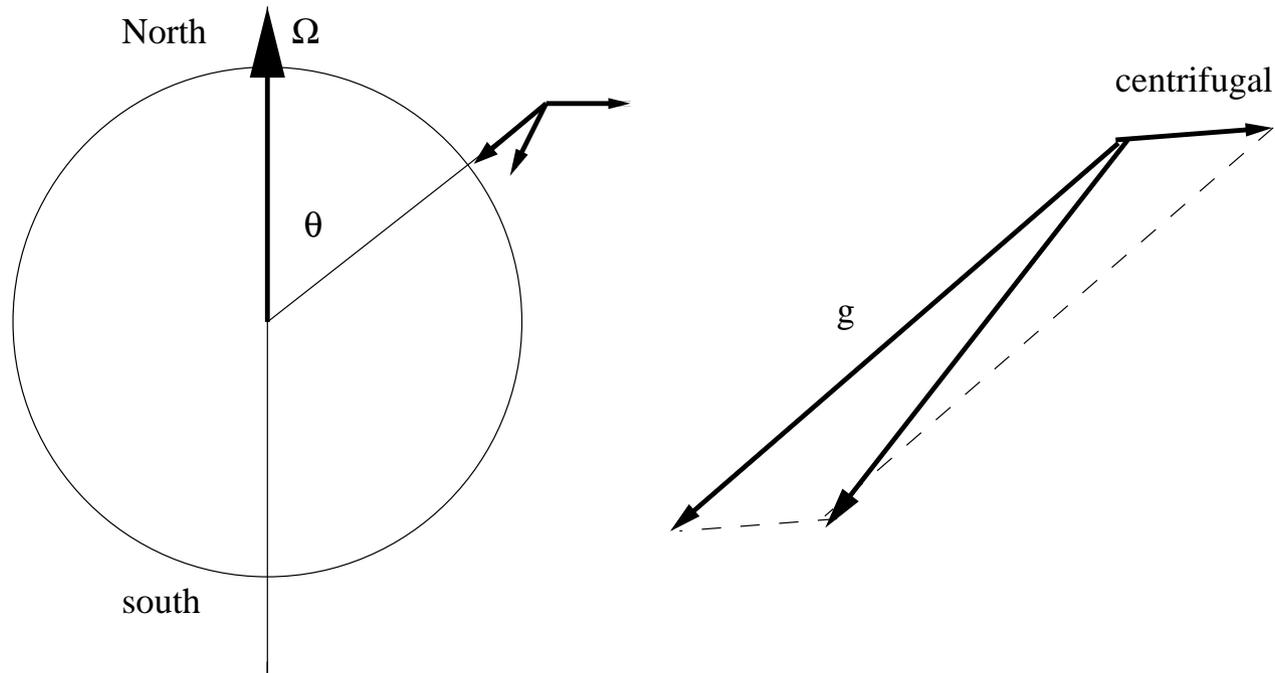
- Angular speed of Earth = 7.27×10^{-5} rad/sec.
- Radius of Earth = 6400 Km = 6.4×10^6 m



- Centrifugal Acceleration at equator is 3.38×10^{-2} m/s/s

Example 3

At an latitude θ , what is vertical?



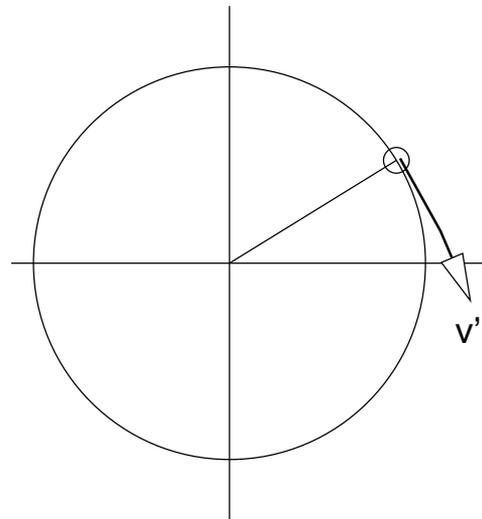
Magnitude of the centrifugal component

$$\Omega^2 R_e \sin \theta$$

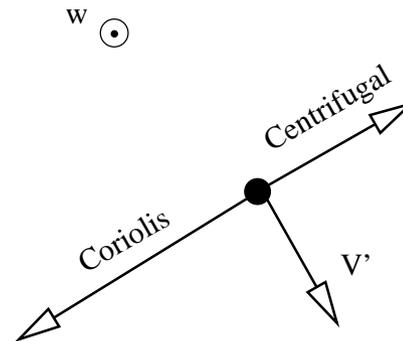
Example 4

Suppose particle is at rest in fixed frame. No Force!

In rotating frame: Circular Trajectory with angular velocity $-\vec{\omega}$. Centrifugal force is same as before and is $m\omega^2 r' \hat{\mathbf{r}}'$! But since u' is non-zero, coriolis term is $-2m\omega^2 r' \hat{\mathbf{r}}'$. So resultant pseudoforce is $-m\omega^2 r' \hat{\mathbf{r}}'$.



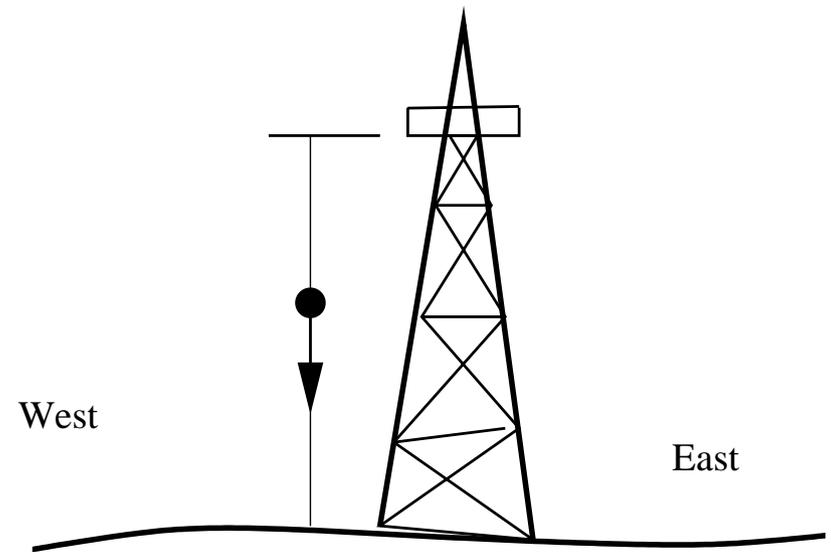
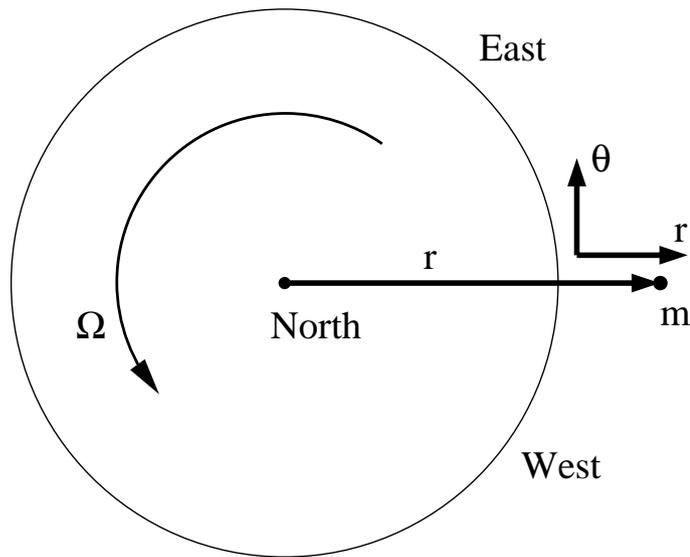
Rotating Frame



Example 5

A ball is dropped from a tower at equator. (Neglect Air Resistance, Shape of the earth etc.)

Setup a coordinate system in equatorial plane as shown in the figure.



Example Continued...

Equations of Motion are given by

$$\mathbf{F} = -mg\hat{\mathbf{r}} - 2m\boldsymbol{\Omega} \times \mathbf{v} - m\boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r})$$

If the velocity of the particle is $\mathbf{v} = \dot{r}\hat{\mathbf{r}} + r\dot{\theta}\hat{\boldsymbol{\theta}}$, two components of the force are given by

$$F_r = -mg + 2m\Omega\dot{\theta}r + m\Omega^2r$$

$$F_\theta = -2m\dot{r}\Omega$$

Example Continued...

Approximations

- Ball falls almost vertically, so the deflection and velocity in horizontal component (θ direction) is very small.
- g is constant, since the ball falls from $R_e + h$ to R_e .

The radial equation is

$$m \left(\ddot{r} - mr\dot{\theta}^2 \right) = -mg + 2m\Omega\dot{\theta}r + m\Omega^2r$$

$$m\ddot{r} = -mg + m\Omega^2r$$

$$\ddot{r} = -g$$

Time taken to fall is $\sqrt{2h/g}$.

Example Continued...

The tangential equation is

$$m \left(r\ddot{\theta} + 2m\dot{r}\dot{\theta} \right) = -2m\dot{r}\Omega$$

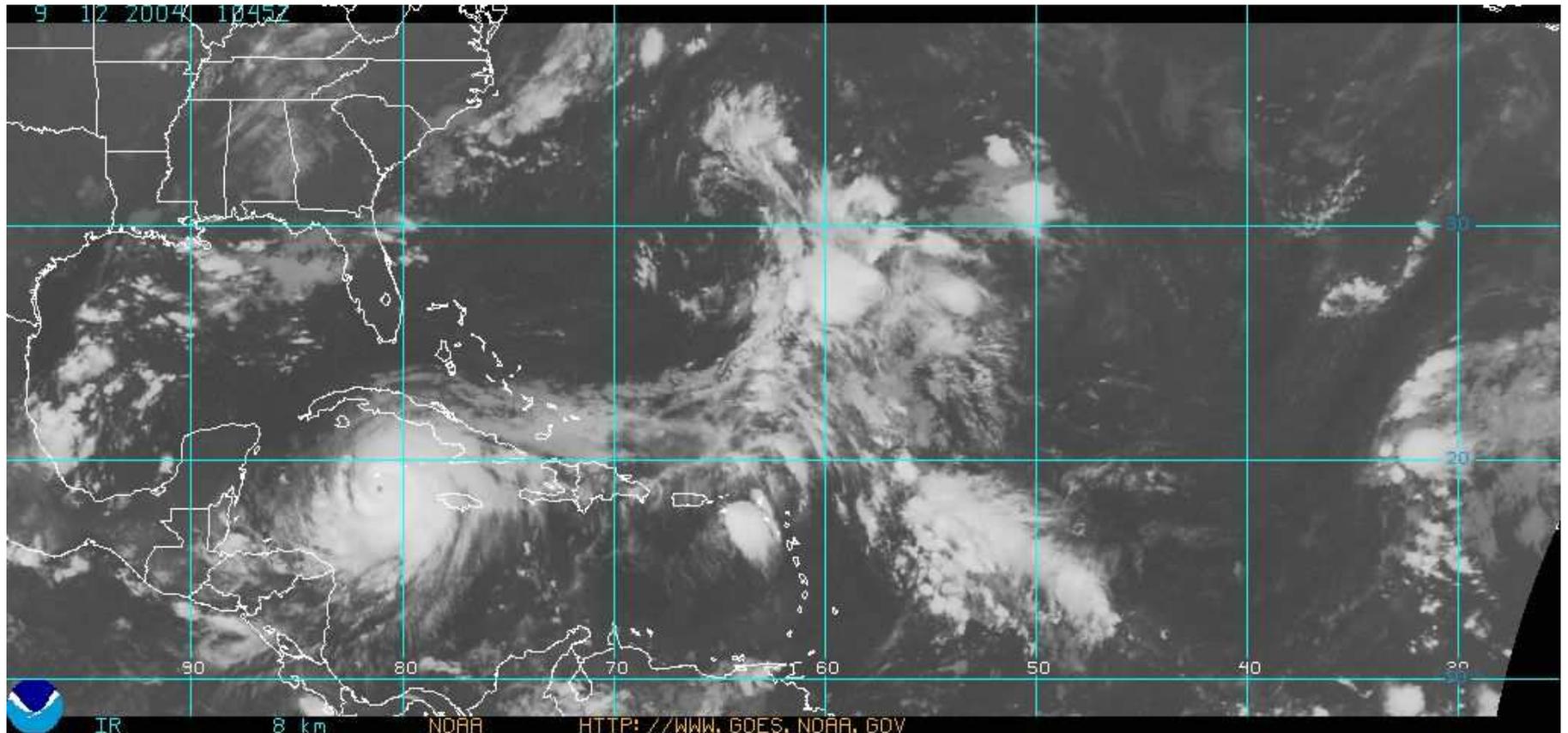
$$R_e\ddot{\theta} = -2\dot{r}\Omega$$

$$\ddot{\theta} = \frac{2g\Omega}{R_e}t$$

So $\theta = \frac{g\Omega t^3}{3}$. In time T , the deflection to the east will be

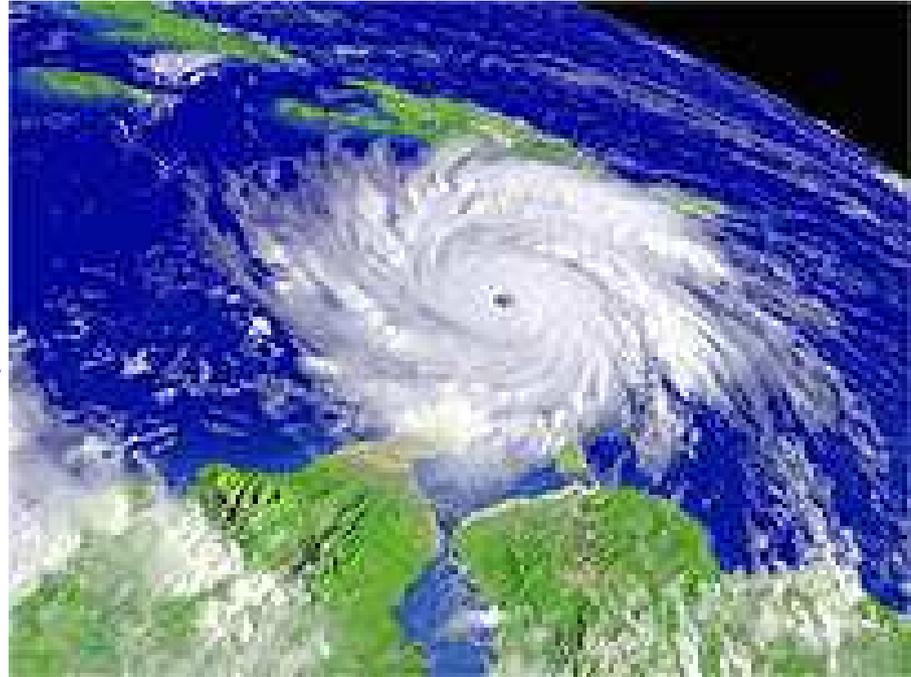
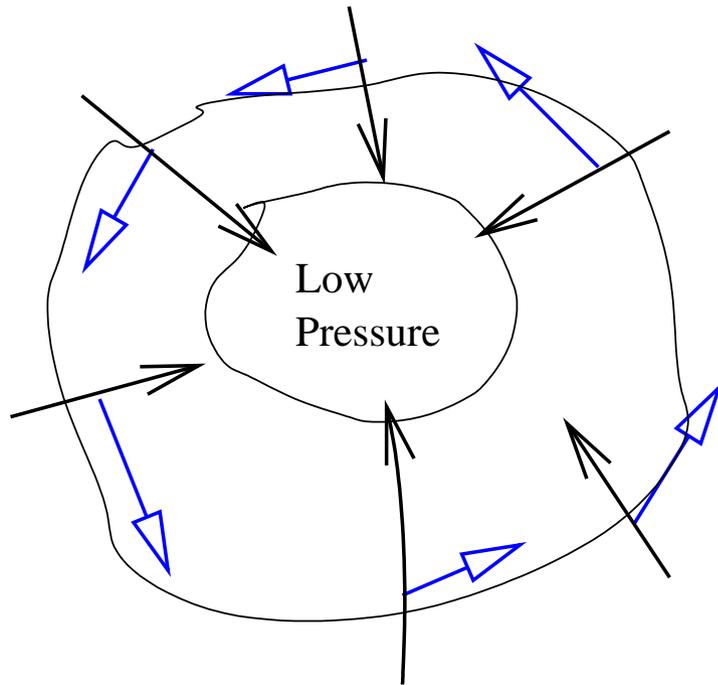
$$y = \frac{1}{3}g\Omega \left(\frac{2h}{g} \right)^{2/3}$$

Hurricanes



Hurricane Ivan presently over Jamaica and is heading for Cuba. Picture was taken on 12/9/04.

Hurricanes



As the air moves in to a low pressure area, coriolis force deflects it to right before being sucked in, causing a counter-clockwise spinning motion. In southern hemisphere the spin would be clockwise.